

# Simplest random walks for boundary value problems

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# Plan of the talk

- Introduction
- Dirichlet problem for parabolic and elliptic linear PDEs  
[Milstein, T 2002]
- Robin problem for parabolic and elliptic linear PDEs  
[Leimkuhler, Sharma, T 2022?]
- Dirichlet problem for linear PIDEs [Deligiannidis, Maurer, T, 2021]
- Conclusions

$$L := \frac{\partial}{\partial t} + \frac{1}{2} \sum_{r=1}^q \sum_{i,j=1}^d \sigma_r^i \sigma_r^j \frac{\partial^2}{\partial x^i \partial x^j} + \sum_{i=1}^d b^i \frac{\partial}{\partial x^i} \quad (1)$$

The Cauchy problem for linear parabolic PDE:

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where  $X_{t_0, x}(t)$ ,  $t \geq t_0$ , is the solution of the Ito SDEs

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# Introduction

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Approximation:

$$u \equiv Ef(X(T)) \simeq \bar{u} \equiv Ef(X_N) \simeq \hat{u} \equiv \frac{1}{M} \sum_{m=1}^M f(X_N^{(m)}), \quad (6)$$

where  $X_N^{(m)}$ ,  $m = 1, \dots, M$ , are independent realizations of  $X_N$ .

## Definition

If an approximation  $\bar{X}$  is such that

$$|Ef(\bar{X}(T)) - Ef(X(T))| \leq Kh^p \quad (7)$$

for  $f$  from a class of functions with polynomial growth at infinity, then we say that the **weak order of accuracy** of the approximation  $\bar{X}$  (the method  $\bar{X}$ ) is  $p$ . The constant  $K$  depends on the SDE coefficients, on the function  $f$  and on  $T$ .

The *weak Euler scheme* (Milstein (1978))

$$X_{k+1} = X_k + b_k h + \sqrt{h} \sum_{r=1}^q \sigma_{rk} \eta_{rk}, \quad (8)$$

where  $\eta_{rk}$ ,  $r = 1, \dots, q$ ,  $k = 0, \dots, N-1$ , are independent random variables taking the values  $+1$  and  $-1$  with probabilities  $1/2$ , also has first order of accuracy in the sense of weak approximation.

[e.g. Milstein, T.; Springer, 2004 or 2021]

# Dirichlet problem

Let  $G$  be a bounded domain in  $\mathbf{R}^d$  and  $Q = [T_0, T) \times G \subset \mathbf{R}^{d+1}$ , and  $\Gamma = \bar{Q} \setminus Q$ . Consider the Dirichlet problem

$$\frac{\partial u}{\partial t} + \frac{1}{2} \sum_{i,j=1}^d a^{ij}(t,x) \frac{\partial^2 u}{\partial x^i \partial x^j} + \sum_{i=1}^d b^i(t,x) \frac{\partial u}{\partial x^i} + c(t,x)u \quad (9)$$

$$+g(t,x) = 0, \quad (t,x) \in Q,$$

$$u|_{\Gamma} = \varphi(t,x). \quad (10)$$



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The probabilistic representation:

$$u(t, x) = E[\varphi(\tau, X_{t,x}(\tau))Y_{t,x,1}(\tau) + Z_{t,x,1,0}(\tau)], \quad (11)$$

where  $X_{t,x}(s)$ ,  $Y_{t,x,y}(s)$ ,  $Z_{t,x,y,z}(s)$ ,  $s \geq t$ , is the solution of the SDEs:

$$dX = (b(s, X) - \sigma(s, X)\mu(s, X)) ds + \sigma(s, X) dw(s), \quad X(t) = x, \quad (12)$$

$$dY = c(s, X)Y ds + \mu^\top(s, X)Y dw(s), \quad Y(t) = y, \quad (13)$$

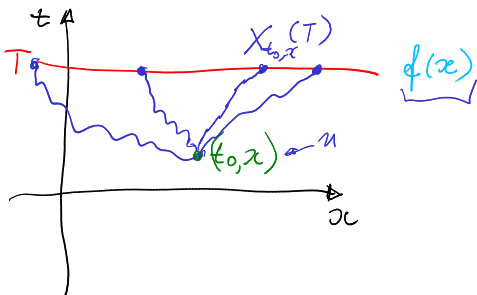
$$dZ = g(s, X)Y ds + F^\top(s, X)Y dw(s), \quad Z(t) = z, \quad (14)$$

$(t, x) \in Q$ ,  $\tau = \tau_{t,x}$  is the first exit time of  $(s, X_{t,x}(s))$  to  $\Gamma$ ,  $w(s) = (w^1(s), \dots, w^d(s))^\top$  is a standard Wiener process, the  $d \times d$  matrix  $\sigma(s, x)$  is obtained from  $\sigma(s, x)\sigma^\top(s, x) = a(s, x)$ ,  $\mu(s, x)$  and  $F(s, x)$  are arbitrary  $d$ -dimensional vectors sufficiently smooth in  $\bar{Q}$ .

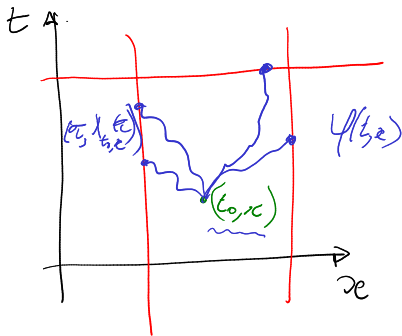


# Cauchy vs Dirichlet problem

Cauchy



Dirichlet



## Dirichlet problem: approximation

*Weak approximation of stopped diffusions:* Milstein (1995), Costantini, Pacchiarotti, Satoretto (1998), Gobet (2000), [Milstein, T \(2002\)](#) and [also Springer 2004 or 2021](#), Gobet, Menozzi (2010)

Apply the weak Euler approximation with the simplest simulation of noise to the system (12)-(14)

$$X_{t,x}(t+h) \approx X = x + h(b(t,x) - \sigma(t,x)\mu(t,x)) + h^{1/2}\sigma(t,x)\xi, \quad (15)$$

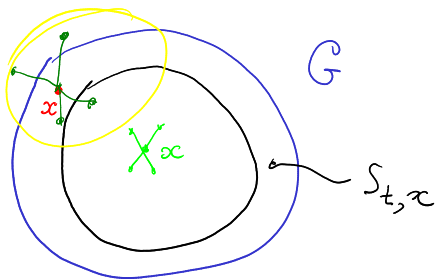
$$Y_{t,x,y}(t+h) \approx Y = y + hc(t,x)y + h^{1/2}\mu^\top(t,x)y\xi, \quad (16)$$

$$Z_{t,x,y,z}(t+h) \approx Z = z + hg(t,x)y + h^{1/2}F^\top(t,x)y\xi, \quad (17)$$

where  $\xi = (\xi^1, \dots, \xi^d)^\top$ ,  $\xi^i$ ,  $i = 1, \dots, d$ , are mutually independent random variables taking the values  $\pm 1$  with probability  $1/2$ .

# Dirichlet problem: the simplest random walk

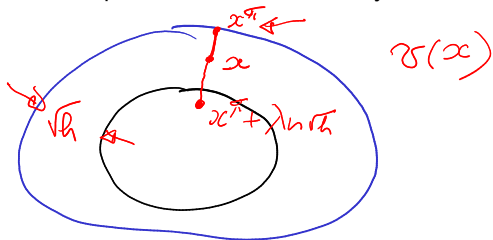
Introduce the set of points close to the boundary (a boundary zone)  
 $S_{t,h} \subset \bar{G}$  on the layer  $t$ : we say that  $x \in S_{t,h}$  if at least one of the  $2^d$  values of the vector  $X$  is outside  $\bar{G}$ . It is not difficult to see that due to compactness of  $\bar{Q}$  there is a constant  $\lambda > 0$  such that if the distance from  $x \in G$  to the boundary  $\partial G$  is equal to or greater than  $\lambda\sqrt{h}$  then  $x$  is outside the boundary zone and, therefore, for such  $x$  all the realizations of the random variable  $X$  belong to  $\bar{G}$ .



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Since restrictions connected with nonexit from the domain  $\bar{G}$  should be imposed on an approximation of the system (12), the formulas (15)-(17) can be used only for the points  $x \in \bar{G} \setminus S_{t,h}$  on the layer  $t$ , and a special construction is required for points from the boundary zone.



## Dirichlet problem: the simplest random walk

Let  $x \in S_{t,h}$ . Denote by  $x^\pi \in \partial G$  the projection of the point  $x$  on the boundary of the domain  $G$  (the projection is unique because  $h$  is sufficiently small and  $\partial G$  is smooth) and by  $n(x^\pi)$  the unit vector of internal normal to  $\partial G$  at  $x^\pi$ . Introduce the random vector  $X_{x,h}^\pi$  taking two values  $x^\pi$  and  $x + h^{1/2}\lambda n(x^\pi)$  with probabilities  $p = p_{x,h}$  and  $q = q_{x,h} = 1 - p_{x,h}$ , respectively, where

$$p_{x,h} = \frac{h^{1/2}\lambda}{|x + h^{1/2}\lambda n(x^\pi) - x^\pi|}.$$

If  $v(x)$  is a twice continuously differentiable function with the domain of definition  $\bar{G}$ , then an approximation of  $v(x)$  by the expectation  $Ev(X_{x,h}^\pi)$  corresponds to linear interpolation and

$$v(x) = Ev(X_{x,h}^\pi) + \mathcal{O}(h) = pv(x^\pi) + qv(x + h^{1/2}\lambda n(x^\pi)) + \mathcal{O}(h). \quad (18)$$

We emphasize that the second value  $x + h^{1/2}\lambda n(x^\pi)$  does not belong to the boundary zone. We also note that  $p$  is always greater than  $1/2$  (since the distance from  $x$  to  $\partial G$  is less than  $h^{1/2}\lambda$ ) and that if  $x \in \partial G$  then  $p = 1$  (since in this case  $x^\pi = x$ ).

# Dirichlet problem: the simplest random walk algorithm

- STEP 0.  $X'_0 = x_0, Y_0 = 1, Z_0 = 0, k = 0.$
- STEP 1. If  $X'_k \notin S_{t_k, h}$  then  $X_k = X'_k$  and go to STEP 3.  
If  $X'_k \in S_{t_k, h}$  then either  $X_k = X_k'^{\pi}$  with probability  $p_{X'_k, h}$  or  $X_k = X'_k + h^{1/2} \lambda n(X_k'^{\pi})$  with probability  $q_{X'_k, h}.$
- STEP 2. If  $X_k = X_k'^{\pi}$  then STOP and  $\varkappa = k,$   
 $X_{\varkappa} = X_k'^{\pi}, Y_{\varkappa} = Y_k, Z_{\varkappa} = Z_k.$
- STEP 3. Simulate  $\xi_k$  and find  $X'_{k+1}, Y_{k+1}, Z_{k+1}$  according to (15)-(17) for  $t = t_k, x = X_k, y = Y_k, z = Z_k,$   
 $\xi = \xi_k.$
- STEP 4. If  $k + 1 = N,$  STOP and  $\varkappa = N, X_{\varkappa} = X'_N, Y_{\varkappa} = Y_N,$   
 $Z_{\varkappa} = Z_N,$  otherwise  $k := k + 1$  and return to STEP 1.

# Dirichlet problem: the simplest random walk

## Theorem

*Algorithm has weak order of accuracy  $O(h)$ , i.e., the inequality*

$$|E(\varphi(t_x, X_x) Y_x + Z_x) - u(t_0, x_0)| \leq Ch \quad (19)$$

*holds with  $C > 0$  independent of  $t_0, x_0, h$ .*

## The scheme of the proof:

- Lemma on order  $\mathcal{O}(h^2)$  for the one-step approximation for the Euler approximation.  
The number of steps when  $X'_k \notin S_{t_k, h}$  is obviously  $\mathcal{O}(1/h)$ .
- Lemma on local order  $\mathcal{O}(h)$  when  $X'_k$  goes outside  $\bar{G}$ .
- Lemma on the average number of steps when  $X'_k \in S_{t_k, h}$  is finite.

Milstein, T (2002) and also Springer 2004 or 2021

# Dirichlet problem for elliptic PDE

Consider the Dirichlet problem for elliptic equation

$$\frac{1}{2} \sum_{i,j=1}^d a^{ij}(x) \frac{\partial^2 u}{\partial x^i \partial x^j} + \sum_{i=1}^d b^i(x) \frac{\partial u}{\partial x^i} + c(x) u + g(x) = 0, \quad x \in G, \quad (20)$$

$$u|_{\partial G} = \varphi(x). \quad (21)$$

The probabilistic representation:

$$u(x) = E [\varphi(X_x(\tau)) Y_{x,1}(\tau) + Z_{x,1,0}(\tau)], \quad (22)$$

where  $X_x(s)$ ,  $Y_{x,y}(s)$ ,  $Z_{x,y,z}(s)$ ,  $s \geq 0$ , is the solution of the Cauchy problem for the system of SDEs:

$$dX = (b(X) - \sigma(X)\mu(X)) ds + \sigma(X) dw(s), \quad X(0) = x, \quad (23)$$

$$dY = c(X)Y ds + \mu^\top(X)Y dw(s), \quad Y(0) = y, \quad (24)$$

$$dZ = g(X)Y ds + F^\top(X)Y dw(s), \quad Z(0) = z, \quad (25)$$

$x \in G$ , and  $\tau = \tau_x$  is the first exit time of the trajectory  $X_x(s)$  to the boundary  $\partial G$ .



# Dirichlet problem for elliptic PDE

To approximate the solution of the system (23), we construct a Markov chain  $X_k$  which stops when it reaches the boundary  $\partial G$  at a random step  $\varkappa$ .

- The simplest random walk is similar to the parabolic case, except  $\varkappa$  can be large
- First-order convergence proved.

Milstein, T (2002) and also Springer 2004 or 2021

# Robin problem

Let  $G \in \mathbb{R}^d$  be a bounded domain with boundary  $\partial G$  and  $Q := [T_0, T) \times G$  be a cylinder in  $\mathbb{R}^{d+1}$ .

Consider the Robin problem:

$$\frac{\partial u}{\partial t} + \frac{1}{2} \sum_{i,j=1}^d a^{ij}(t, x) \frac{\partial u}{\partial x^i} \frac{\partial u}{\partial x^j} + \sum_{i=1}^d b^i(t, x) \frac{\partial u}{\partial x^i} + c(t, x)u + g(t, x) = 0, \quad (t, x) \in Q, \quad (26)$$

$$u(T, x) = \varphi(x), \quad x \in \bar{G}, \quad (27)$$

$$\frac{\partial u}{\partial \nu} + \gamma(t, z)u = \psi(t, z), \quad (t, z) \in S, \quad (28)$$

where  $\nu = \nu(z)$  is the direction of the inner normal to the surface  $\partial G$  at  $z \in \partial G$ .

## Robin problem

The probabilistic representation [Gikhman, Skorohod 1968, Ikeda, Watanabe 1981, Freidlin 1985]:

$$u(t_0, x) = \mathbb{E}(\varphi(X_{t_0,x}(T))Y_{t_0,x,1}(T) + Z_{t_0,x,1,0}(T)), \quad (29)$$

where  $X_{t_0,x}(s)$ ,  $Y_{t_0,x,y}(s)$ ,  $Z_{t_0,x,y,z}(s)$ ,  $s \geq t_0$ , is the solution of the system of RSDEs

$$dX(s) = b(s, X(s))ds + \sigma(s, X(s))dW(s) + \nu(X(s))I_{\partial G}(X(s))dL(s), \quad (30)$$

$$dY(s) = c(s, X(s))Y(s)ds + \gamma(s, X(s))I_{\partial G}(X(s))Y(s)dL(s), \quad (31)$$

$$dZ(s) = g(s, X(s))Y(s)ds - \psi(s, X(s))I_{\partial G}(X(s))Y(s)dL(s), \quad (32)$$

with  $X(t_0) = x$ ,  $Y(t_0) = y$ ,  $Z(t_0) = z$ ,  $T_0 \leq t_0 \leq s \leq T$ ,  $x \in \bar{G}$ .

## Robin problem

$L(s)$  is the local time of the process  $X(s)$  on the boundary  $\partial G$  adapted to the filtration  $(\mathcal{F}_s)_{s \geq 0}$ . A local time is a scalar increasing process continuous in  $s$  which increases only when  $X(s) \in \partial G$ :

$$L(t) = \int_{t_0}^t I_{\partial G}(X(s)) dL(s),$$

[Ikeda, Watanabe 1981; P.L. Lions, A.S. Sznitman 1984; Freidlin 1985]

$$L(t) = \int_0^t \delta(w(s)) ds$$

# Robin problem: approximation of RSDE

*Weak approximation of RSDEs:*

Y. Liu (1993); G.N. Milstein (1997); C. Costantini, B. Pacchiarotti, F. Sartoretto (1998); E. Gobet (2001); M. Bossy, E. Gobet, and D. Talay (2004), [Leimkuhler, Sharma, T \(2022?\)](#)

Let  $(t_0, x) \in Q$ . We introduce the uniform discretization of the time interval  $[t_0, T]$  so that  $t_0 < \dots < t_N = T$ ,  $h := (T - t_0)/N$  and  $t_{k+1} = t_k + h$ .

We consider a Markov chain  $(X_k)_{k \geq 0}$  with  $X_0 = x$  approximating the solution  $X_{t_0, x}(t)$  of the RSDEs

$$\begin{aligned}dX(s) &= b(s, X(s))ds + \sigma(s, X(s))dW(s) + \nu(X(s))I_{\partial G}(X(s))dL(s), \\ X(t_0) &= x.\end{aligned}$$

Since  $X(t)$  cannot take values outside  $\bar{G}$ , the Markov chain should remain in  $\bar{G}$  as well. To this end, the chain has an auxiliary (intermediate) step every time it moves from the time layer  $t_k$  to  $t_{k+1}$ .

## Easy-to-implement algorithm

We denote this auxiliary step by  $X'_{k+1}$ . In moving from  $X_k$  to  $X'_{k+1}$ , we apply the weak Euler scheme

$$X'_{k+1} = X_k + hb_k + h^{1/2}\sigma_k\xi_{k+1}, \quad (33)$$

where  $b_k = b(t_k, X_k)$ ,  $\sigma_k = \sigma(t_k, X_k)$  and  $\xi_{k+1} = (\xi_{k+1}^1, \dots, \xi_{k+1}^d)^\top$ ,  $\xi_{k+1}^i$ ,  $i = 1, \dots, d$ ,  $k = 0, \dots, N-1$ , are mutually independent random variables taking values  $\pm 1$  with probability  $1/2$ .

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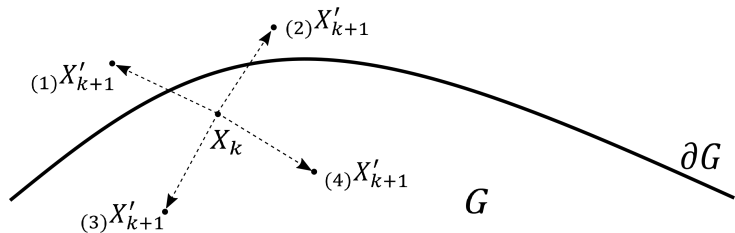
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Taking this auxiliary step  $X'_{k+1}$  while moving from  $X_k$  to  $X_{k+1}$  portrays cautious behaviour and gives us an opportunity to check whether the realized value of  $X'_{k+1}$  is inside the domain  $G$  or not. If  $X'_{k+1} \in \bar{G}$  then on the same time layer we assign values to  $X_{k+1}$  as

$$X_{k+1} = X'_{k+1}$$

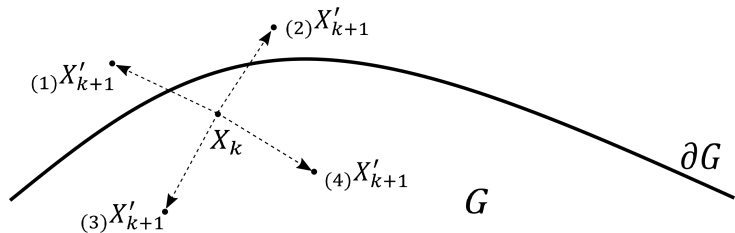
# Easy-to-implement algorithm



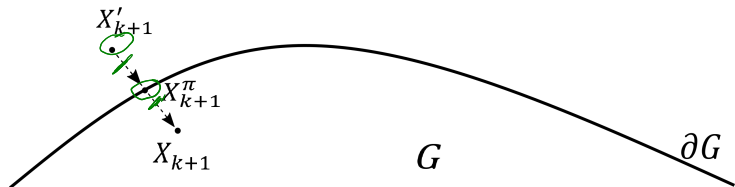
Four possible realizations  $(i)X'_{k+1}$  of  $X'_{k+1}$  given  $X_k$  in two dimensions.



# Easy-to-implement algorithm

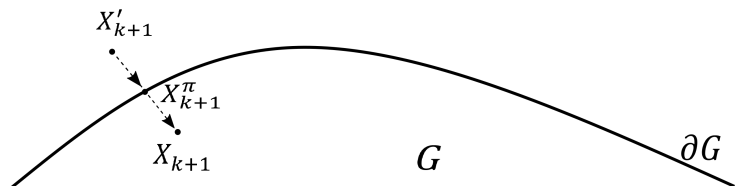


Four possible realizations  $(i)X'_{k+1}$  of  $X'_{k+1}$  given  $X_k$  in two dimensions.



One step transition in two dimensions from  $X'_{k+1}$  to  $X_{k+1}$  using projection  $X^{\pi}_{k+1}$  of  $X'_{k+1}$  on  $\partial G$ .

# Easy-to-implement algorithm



One step transition in two dimensions from  $X'_{k+1}$  to  $X_{k+1}$  using projection  $X^{\pi}_{k+1}$  of  $X'_{k+1}$  on  $\partial G$ .

We find the projection of  $X'_{k+1}$  onto  $\partial G$  which we denote as  $X^{\pi}_{k+1}$  and we calculate  $r_{k+1} = \text{dist}(X'_{k+1}, X^{\pi}_{k+1})$  which is the shortest distance between  $X'_{k+1}$  and  $X^{\pi}_{k+1}$ . Note that  $\text{dist}(X_k, X'_{k+1}) = \mathcal{O}(h^{1/2})$ .

$$X_{k+1} = X'_{k+1} + 2r_{k+1}\nu(X^{\pi}_{k+1}). \quad (34)$$

# Easy-to-implement algorithm

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**Algorithm 1** Algorithm to approximate normal reflected diffusion

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Step 1: Set  $X_0 = x$ ,  $X'_0 = x$ ,  $k = 0$ .

Step 2: Simulate  $\xi_{k+1}$  and find  $X'_{k+1}$  using (33).

Step 3: **If**  $X'_{k+1} \in \bar{G}$  then  $X_{k+1} = X'_{k+1}$ , **else**

(i) find the projection  $X_{k+1}^\pi$  of  $X'_{k+1}$  on  $\partial G$ ,

(ii) calculate  $r_{k+1} = \text{dist}(X'_{k+1}, X_{k+1}^\pi)$  and find  $X_{k+1}$  according to (34).

Step 4: **If**  $k + 1 = N$  then **stop**, **else** put  $k := k + 1$  and **return** to Step 2.

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## Easy-to-implement algorithm

We approximate RSDEs (30) according to Algorithm 1 and complement it by an approximation of (31) and (32). If the intermediate step  $X'_{k+1}$  introduced in Algorithm 1, belongs to  $\bar{G}$  then we use the Euler scheme:

$$Y_{k+1} = Y_k + hc(t_k, X_k)Y_k \quad (35)$$

$$Z_{k+1} = Z_k + hg(t_k, X_k)Y_k. \quad (36)$$

If  $X'_{k+1} \notin \bar{G}$  then

$$Y_{k+1} = Y_k + hc(t_k, X_k)Y_k + 2r_{k+1}\gamma(t_{k+1}, X_{k+1}^\pi)Y_k + 2r_{k+1}^2\gamma^2(t_{k+1}, X_{k+1}^\pi)Y_k, \quad (37)$$

$$Z_{k+1} = Z_k + hg(t_k, X_k)Y_k - 2r_{k+1}\psi(t_{k+1}, X_{k+1}^\pi)Y_k - 2r_{k+1}^2\psi(t_{k+1}, X_{k+1}^\pi)\gamma(t_{k+1}, X_{k+1}^\pi)Y_k, \quad (38)$$

where  $X_{k+1}^\pi$  is the projection of  $X'_{k+1}$  on  $\partial G$  and  $r_{k+1} = \text{dist}(X'_{k+1}, X_{k+1}^\pi)$ .

---

**Algorithm 2** Algorithm to approximate the Robin problem

---

Step 1: Set  $X_0 = x$ ,  $Y_0 = 1$ ,  $Z_0 = 0$ ,  $X'_0 = x$ ,  $k = 0$ .

Step 2: Simulate  $\xi_{k+1}$  and find  $X'_{k+1}$  using (33).

Step 3: **If**  $X'_{k+1} \in \bar{G}$  **then**  $X_{k+1} = X'_{k+1}$  and calculate  $Y_{k+1}$  and  $Z_{k+1}$  according to (35) and (36), respectively, **else** find  $X_{k+1}$ ,  $Y_{k+1}$  and  $Z_{k+1}$  according to (34), (37) and (38), respectively.

Step 4: **If**  $k + 1 = N$  **then stop**, **else** put  $k := k + 1$  and **return** to Step 2.

---

## Theorem

*The weak order of accuracy of the Algorithm is  $\mathcal{O}(h)$  under some assumptions, i.e., for sufficiently small  $h > 0$*

$$|\mathbb{E}(\varphi(X_N)Y_N + Z_N) - u(t_0, X_0)| \leq Ch, \quad (39)$$

*where  $u(t, x)$  is solution of (26)-(28) and  $C$  is a positive constant independent of  $h$ .*

The scheme of the proof is roughly as follows.

- Lemma on order  $\mathcal{O}(h^2)$  for the one-step approximation for the intermediate step  $X'_{k+1}$  (i.e., of the Euler approximation).  
The number of steps when  $X'_{k+1} \in \bar{G}$  is obviously  $\mathcal{O}(1/h)$ .
- Lemma on local order  $\mathcal{O}(h^{3/2})$  for  $X_{k+1}$  when  $X'_{k+1}$  goes outside  $\bar{G}$ .
- Lemma on the average number of steps when  $X'_{k+1} \notin \bar{G}$  is  $\mathcal{O}(1/\sqrt{h})$ .

Leimkuhler, Sharma, T (2022?)

# Elliptic PDEs with Robin boundary condition

Let  $c(x)$  be negative for all  $x \in \bar{G}$  and  $\gamma(z)$  be non-positive for all  $z \in \partial G$ . Consider the elliptic equation

$$\frac{1}{2} \sum_{i,j=1}^d a^{ij}(x) \frac{\partial^2 u}{\partial x^i \partial x^j} + \sum_{i=1}^d b^i(x) \frac{\partial u}{\partial x^i} + c(x)u + g(x) = 0, \quad x \in G, \quad (40)$$

with Robin boundary condition

$$\frac{\partial u}{\partial \nu} + \gamma(z)u = \psi(z), \quad z \in \partial G, \quad (41)$$

The probabilistic representation [Freidlin 1985]:

$$u(x) = \lim_{T \rightarrow \infty} \mathbb{E} \left( Z_x(T) \right),$$

where  $Z_x(s)$ ,  $x \in \bar{G}$ , is governed by the RSDEs

$$dX(s) = b(X(s))ds + \sigma(X(s))dW(s) + \nu(X(s))I_{\partial G}(X(s))dL(s), \quad X(0) = x,$$

$$dY(s) = c(X(s))Y(s)ds + \gamma(X(s))I_{\partial G}(X(s))Y(s)dL(s), \quad Y(0) = 1,$$

$$dZ(s) = g(X(s))Y(s)ds - \psi(X(s))I_{\partial G}(X(s))Y(s)dL(s), \quad Z(0) = 0.$$

$$\sigma(x)\sigma(x)^\top = a(x).$$

## Theorem

*Under some assumptions, the following inequality holds for sufficiently small  $h > 0$ :*

$$|\mathbb{E}(Z_N) - u(x)| \leq C (h + e^{-\lambda T}), \quad (42)$$

*where  $Z_N$  is calculated according to Algorithm 2 approximating the solution  $u(x)$  of (40)-(41), and  $C$  and  $\lambda$  are positive constants independent of  $T$  and  $h$ .*

Leimkuhler, Sharma, T (2022?)



**The case**  $c(x) = 0$  **and**  $\gamma(z) = 0$ . The probabilistic representation [Freindlin 1985; Bencherif-Madani, Pardoux 2009]:

$$u(x) = \lim_{T \rightarrow \infty} \mathbb{E}Z_x(T) + \bar{u}, \quad (43)$$

where  $\bar{u} = \int_G u(x)\rho(x)dx$ ,  $\rho(x)$  is the solution of the adjoint problem (note that  $\rho(x)$  is the invariant density of  $X(s)$ ), and  $Z_x(s) = Z(s)$  is governed by

$$dZ(s) = -\phi_1(X(s))ds - \phi_2(X(s))I_{\partial G}(X(s))dL(s), \quad Z(0) = 0,$$

where  $X(s)$  is as before.

A suitable algorithm based on double partitioning of the time interval  $[0, T]$  and its convergence proof are in [Leimkuhler, Sharma, T \(2022?\)](#).

# Dirichlet problem for parabolic integro-differential equation

Let  $G$  be a bounded domain in  $\mathbb{R}^d$ ,  $Q = [t_0, T] \times G$  be a cylinder in  $\mathbb{R}^{d+1}$ ,  $\Gamma = \bar{Q} \setminus Q$ ,  $G^c = \mathbb{R}^d \setminus G$  be the complement of  $G$  and  $Q^c := (t_0, T] \times G^c \cup \{T\} \times \bar{G}$ . Consider the Dirichlet problem for the PIDE:

$$\begin{aligned} \frac{\partial u}{\partial t} + Lu + c(t, x)u + g(t, x) &= 0, \quad (t, x) \in Q, \\ u(t, x) &= \varphi(t, x), \quad (t, x) \in Q^c, \end{aligned} \quad (44)$$

$$Lu(t, x) := \frac{1}{2} \sum_{i,j=1}^d a^{ij}(t, x) \frac{\partial^2 u}{\partial x^i \partial x^j}(t, x) + \sum_{i=1}^d b^i(t, x) \frac{\partial u}{\partial x^i}(t, x) \quad (45)$$

$$+ \int_{\mathbb{R}^m} \left\{ u(t, x + F(t, x)z) - u(t, x) - \langle F(t, x)z, \nabla u(t, x) \rangle \mathbf{1}_{|z| \leq 1} \right\} \nu(dz);$$

$F(t, x) = (F^{ij}(t, x))$  is a  $d \times m$ -matrix; and  $\nu(z)$ ,  $z \in \mathbb{R}^m$ , is a Lévy measure such that  $\int_{\mathbb{R}^m} (|z|^2 \wedge 1) \nu(dz) < \infty$ . We allow  $\nu$  to be of infinite intensity, i.e.  $\nu(B(0, r)) = \infty$  for some  $r > 0$ , where  $B(x, s)$  is the open ball of radius  $s > 0$  centred at  $x \in \mathbb{R}^d$ .

# Dirichlet problem for PIDE

Probabilistic representation [Applebaum 2009]

$$u(t, x) = \mathbb{E} [\varphi(\tau_{t,x}, X_{t,x}(\tau_{t,x})) Y_{t,x,1}(\tau_{t,x}) + Z_{t,x,1,0}(\tau_{t,x})], \quad (t, x) \in Q, \quad (46)$$

$$\begin{aligned} dX &= b(s, X(s-))ds + \sigma(s, X(s-))dw(s) \\ &+ \int_{\mathbb{R}^d} F(s, X(s-))z \hat{N}(dz, ds), \quad X_{t,x}(t) = x, \end{aligned} \quad (47)$$

$$dY = c(s, X(s-))Yds, \quad Y_{t,x,y}(t) = y, \quad (48)$$

$$dZ = g(s, X(s-))Yds, \quad Z_{t,x,y,z}(t) = z, \quad (49)$$

and  $\tau_{t,x} = \inf\{s \geq t : (s, X_{t,x}(s)) \notin Q\}$  is the first exit-time of  $(s, X_{t,x}(s))$  from  $Q$ ,  $\sigma(s, x)\sigma^\top(s, x) = a(s, x)$ ;  $w(t) = (w^1(t), \dots, w^d(t))^\top$  is a standard  $d$ -dimensional Wiener process; and  $\hat{N}$  is a Poisson random measure on  $[0, \infty) \times \mathbb{R}^m$  with intensity measure  $\nu(dz) \times ds$ ,  $\int_{\mathbb{R}^m} (|z|^2 \wedge 1) \nu(dz) < \infty$ , and compensated small jumps, i.e.,

$$\begin{aligned} \hat{N}([0, t] \times B) &= \int_{[0, t] \times B} N(dz, ds) - t\nu(B \cap \{|z| \leq 1\}), \\ &\text{for all } t \geq 0 \text{ and } B \in \mathcal{B}(\mathbb{R}^m). \end{aligned}$$

## Dirichlet problem for PIDE

Consider the approximation of (47), where small jumps are replaced by an appropriate diffusion. [Asmussen, Rosinski (2001); Kohatsu-Higa, Tankov (2010); Kohatsu-Higa, Ortiz-Latorre, Tankov (2013); Deligiannidis, Maurer, T (2021)].

# Dirichlet problem for PIDE

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Let  $\gamma_\epsilon$  be an  $m$ -dimensional vector with the components

$$\gamma_\epsilon^i = \int_{\epsilon \leq |z| \leq 1} z^i \nu(dz); \quad (50)$$

and  $B_\epsilon$  is an  $m \times m$  matrix with the components

$$B_\epsilon^{ij} = \int_{|z| < \epsilon} z^i z^j \nu(dz), \quad (51)$$

while  $\beta_\epsilon$  be obtained from the formula  $\beta_\epsilon \beta_\epsilon^\top = B_\epsilon$ .

# Dirichlet problem for PIDE

## Example (Tempered $\alpha$ -stable Process)

For a tempered stable distribution which has Lévy measure given by

$$\nu(dz) = \left( \frac{C_+ e^{-\lambda_+ z}}{z^{1+\alpha}} \mathbf{1}(z > 0) + \frac{C_- e^{-\lambda_- |z|}}{|z|^{1+\alpha}} \mathbf{1}(z < 0) \right) dz,$$

for  $\alpha \in (0, 2)$  and  $C_+, C_-, \lambda_+, \lambda_- > 0$ : we find that the error from approximating the small jumps by diffusion as in Theorem is of the order  $\mathcal{O}(\epsilon^{3-\alpha})$

$$\lambda_\epsilon := \int_{|z| > \epsilon} \nu(dz) = \mathcal{O}(\epsilon^{-\alpha}), \quad \gamma_\epsilon = \mathcal{O}(\epsilon^{1-\alpha}) \text{ for } \alpha \neq 1 \text{ and } B_\epsilon = \mathcal{O}(\epsilon^{2-\alpha}).$$

# Dirichlet problem for PIDE

Consider the modified jump-diffusion  $\tilde{X}_{t_0,x}(t) = \tilde{X}_{t_0,x}^\epsilon(t)$  defined as

$$\begin{aligned} \tilde{X}_{t_0,x}(t) = x + \int_{t_0}^t \left[ b(s, \tilde{X}(s-)) - F(s, \tilde{X}(s-))\gamma_\epsilon \right] ds + \int_{t_0}^t \sigma(s, \tilde{X}(s-)) dw(s) \\ + \int_{t_0}^t F(s, \tilde{X}(s-))\beta_\epsilon dW(s) + \int_{t_0}^t \int_{|z| \geq \epsilon} F(s, \tilde{X}(s-))zN(dz, ds), \end{aligned} \tag{52}$$

where  $W(t)$  is a standard  $m$ -dimensional Wiener process, independent of  $N$  and  $w$ .

# Dirichlet problem for PIDE

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where  $W(t)$  is a standard  $m$ -dimensional Wiener process, independent of  $N$  and  $w$ .

We observe that, in comparison with (47), in (52) jumps less than  $\epsilon$  in magnitude are replaced by the additional diffusion part. In this way, the new Lévy measure has finite activity allowing us to simulate its events exactly, i.e. in a practical way.



Consequently,

$$u(t, x) \approx u_\epsilon(t, x) := \mathbb{E} \left[ \varphi \left( \tilde{\tau}_{t,x}, \tilde{X}_{t,x}(\tilde{\tau}_{t,x}) \right) \tilde{Y}_{t,x,1}(\tilde{\tau}_{t,x}) + \tilde{Z}_{t,x,1,0}(\tilde{\tau}_{t,x}) \right], \quad (53)$$

$$(t, x) \in Q,$$

where  $\tilde{\tau}_{t,x} = \inf\{s \geq t : (s, \tilde{X}_{t,x}(s)) \notin Q\}$  is the first exit time of the space-time Lévy process  $(s, \tilde{X}_{t,x}(s))$  from the space-time cylinder  $Q$  and  $(\tilde{X}_{t,x}(s), \tilde{Y}_{t,x,y}(s), \tilde{Z}_{t,x,y,z}(s))_{s \geq 0}$  solves the system of SDEs consisting of (52) along with

$$d\tilde{Y} = c(s, \tilde{X}(s-)) \tilde{Y} ds, \quad \tilde{Y}_{t,x,y}(t) = y, \quad (54)$$

$$d\tilde{Z} = g(s, \tilde{X}(s-)) \tilde{Y} ds, \quad \tilde{Z}_{t,x,y,z}(t) = z. \quad (55)$$

## Theorem

*Under some assumptions, for  $0 \leq \epsilon < 1$*

$$|u^\epsilon(t, x) - u(t, x)| \leq K \int_{|z| \leq \epsilon} |z|^3 \nu(dz), \quad (t, x) \in Q, \quad (56)$$

*where  $K > 0$  does not depend on  $t, x, \epsilon$ .*

[Deligiannidis, Maurer, T, 2021]

## Example (Tempered $\alpha$ -stable Process)

For  $\alpha \in (0, 2)$  and  $m = 1$  consider an  $\alpha$ -stable process with Lévy measure given by  $\nu(dz) = z^{-1-\alpha}dz$ . Then

$$\int_{|z| \leq \epsilon} |z|^3 \nu(dy) = \frac{\epsilon^{3-\alpha}}{3-\alpha}.$$

Similarly, for a tempered stable distribution which has Lévy measure given by

$$\nu(dz) = \left( \frac{C_+ e^{-\lambda_+ z}}{z^{1+\alpha}} \mathbf{1}(z > 0) + \frac{C_- e^{-\lambda_- |z|}}{|z|^{1+\alpha}} \mathbf{1}(z < 0) \right) dz,$$

for  $\alpha \in (0, 2)$  and  $C_+, C_-, \lambda_+, \lambda_- > 0$  we find that the error from approximating the small jumps by diffusion as in Theorem is of the order  $\mathcal{O}(\epsilon^{3-\alpha})$ .

# Dirichlet problem for PIDE: Algorithm

Assume that we can exactly sample increments  $\delta$  between jump times with the intensity

$$\lambda_\epsilon := \int_{|z|>\epsilon} \nu(dz) \quad (57)$$

and jump sizes  $J_\epsilon$  are distributed according to the density

$$\rho_\epsilon(z) := \frac{\nu(z) \mathbf{1}_{|z|>\epsilon}}{\lambda_\epsilon}. \quad (58)$$

# Dirichlet problem for PIDE: Algorithm

Fix a time-discretization step  $h > 0$  and suppose the current position of the chain is  $(t, x, y, z)$ . If the jump time increment  $\delta < h$ , we set  $\theta = \delta$ , otherwise  $\theta = h$ , i.e.  $\theta = \delta \wedge h$ .

In the case  $\theta = h$ , we apply the weak explicit Euler approximation with no jumps:

$$\begin{aligned} \tilde{X}_{t,x}(t+\theta) \approx & X = x + \theta \cdot (b(t,x) - F(t,x)\gamma_\epsilon) \\ & + \sqrt{\theta} \cdot (\sigma(t,x)\xi + F(t,x)\beta_\epsilon \eta), \end{aligned} \quad (59)$$

$$\tilde{Y}_{t,x,y}(t+\theta) \approx Y = y + \theta \cdot c(t,x)y, \quad (60)$$

$$\tilde{Z}_{t,x,y,z}(t+\theta) \approx Z = z + \theta \cdot g(t,x)y, \quad (61)$$

where  $\xi = (\xi^1, \dots, \xi^d)^\top$ ,  $\eta = (\eta^1, \dots, \eta^m)^\top$ , with  $\xi^1, \dots, \xi^d$  and  $\eta^1, \dots, \eta^m$  mutually independent random variables, taking the values  $\pm 1$  with equal probability.

In the case of  $\theta < h$ , we replace (59) by the following explicit Euler approximation

$$\begin{aligned} \tilde{X}_{t,x}(t+\theta) \approx & X = x + \theta \cdot (b(t,x) - F(t,x)\gamma_\epsilon) \\ & + \sqrt{\theta} \cdot (\sigma(t,x)\xi + F(t,x)\beta_\epsilon \eta) + F(t,x)J_\epsilon. \end{aligned} \quad (62)$$

# Dirichlet problem for PIDE: Algorithm

Let  $(t_0, x_0) \in Q$ . We aim to find the value  $u^\epsilon(t_0, x_0)$ . Introduce a discretization of the interval  $[t_0, T]$ , for example the equidistant one:  
 $h := (T - t_0)/L$ .

To approximate the solution of the system (52), we construct a Markov chain  $(\vartheta_k, X_k, Y_k, Z_k)$  which stops at a random step  $\varkappa$  when  $(\vartheta_k, X_k)$  exits the domain  $Q$ .

# Dirichlet problem for PIDE: Algorithm

- 1: **Initialize:**  $\vartheta_0 = t_0$ ,  $X_0 = x_0$ ,  $Y_0 = 1$ ,  $Z_0 = 0$ ,  $k = 0$ .
- 2: **while**  $\vartheta_k < T$  or  $X_k \in G$  **do**
- 3:     **Simulate:**  $\xi_k$  and  $\eta_k$  with i.i.d. components taking values  $\pm 1$  with probability  $1/2$  and independently  $I_k \sim \text{Bernoulli}(1 - e^{-\lambda_\epsilon h})$ .
- 4:     **if**  $I_k = 0$ , **then**
- 5:         **Set:**  $\theta_k = h$
- 6:         **Evaluate:**  $X_{k+1}$ ,  $Y_{k+1}$ ,  $Z_{k+1}$  according to (15) – (17).
- 7:     **else**
- 8:         **Sample:**  $\theta_k$  according to the density  $\frac{\lambda_\epsilon e^{-\lambda_\epsilon x}}{1 - e^{-\lambda_\epsilon h}}$ .
- 9:         **Sample:** jump size  $J_{\epsilon,k}$  according to the density (58).
- 10:        **Evaluate:**  $X_{k+1}$ ,  $Y_{k+1}$ ,  $Z_{k+1}$  according to (18), (16), (17).
- 11:     **end if**
- 12:     **Set:**  $\vartheta_{k+1} = \vartheta_k + \theta_k$  and  $k = k + 1$ .
- 13: **end while**
- 14: **Set:**  $X_\varkappa = X_k$ ,  $Y_\varkappa = Y_k$ ,  $Z_\varkappa = Z_k$ ,  $\varkappa = k$ ,  $\vartheta_\varkappa = \vartheta_k$ .
- 15: **if**  $\vartheta_\varkappa < T$  **then Set:**  $\bar{\vartheta}_\varkappa = \vartheta_\varkappa$
- 16: **else Set:**  $\bar{\vartheta}_\varkappa = T$
- 17: **end if**

# Dirichlet problem for PIDE: Algorithm

## Theorem

*Under some assumption, the global error of the Algorithm satisfies the following bound*

$$\begin{aligned} & |\mathbb{E}[\varphi(\bar{v}_x, X_x)Y_x + Z_x] - u^\epsilon(t_0, x_0)| \\ & \leq K(1 + \gamma_\epsilon^2) \left( \frac{1}{\lambda_\epsilon} - h \frac{e^{-\lambda_\epsilon h}}{1 - e^{-\lambda_\epsilon h}} \right) + K \frac{1 - e^{-\lambda_\epsilon h}}{\lambda_\epsilon}, \end{aligned} \quad (63)$$

where  $K > 0$  is a constant independent of  $h$  and  $\epsilon$ .

[Deligiannidis, Maurer, T, 2021]

$$\lambda_\epsilon = \int_{|z| > \epsilon} \nu(dz)$$



# Dirichlet problem for PIDE: Algorithm

If  $\lambda_\epsilon h < 1$ , we obtain:

$$|\mathbb{E}[\varphi(\bar{v}_x, X_x)Y_x + Z_x] - u^\epsilon(t_0, x_0)| \leq K(1 + |\gamma_\epsilon|^2)h,$$

which is expected for weak convergence in the jump-diffusion case.

If  $\lambda_\epsilon$  is large (meaning that almost always  $\theta < h$ ), the error is tending to

$$|\mathbb{E}[\varphi(\bar{v}_x, X_x)Y_x + Z_x] - u^\epsilon(t_0, x_0)| \leq K(1 + |\gamma_\epsilon|^2)\frac{1}{\lambda_\epsilon}.$$

We also remark that for any fixed  $\lambda_\epsilon$ , we have first order convergence when  $h \rightarrow 0$ .

$$\begin{aligned}
 & |\mathbb{E}[\varphi(\bar{v}_{\mathcal{X}}, X_{\mathcal{X}})Y_{\mathcal{X}} + Z_{\mathcal{X}}] - u(t_0, x_0)| & (64) \\
 & \leq K(1 + |\gamma_{\epsilon}|^2) \left( \frac{1}{\lambda_{\epsilon}} - h \frac{e^{-\lambda_{\epsilon}h}}{1 - e^{-\lambda_{\epsilon}h}} \right) + K \frac{1 - e^{-\lambda_{\epsilon}h}}{\lambda_{\epsilon}} + K \int_{|z| \leq \epsilon} |z|^3 \nu(dz).
 \end{aligned}$$

- For  $\alpha \in (0, 1)$  convergence is linear in cost and there is no benefit of restricting jump adapted steps by  $h$ .
- For  $\alpha \in (1, 2)$ , it is beneficial to use restricted jump-adapted steps to get the order of  $(3 - \alpha)/(1 + \alpha)$  in cost.
- Restricted jump-adapted steps should typically be used for jump-diffusions (the finite activity case when there is no singularity of  $\lambda_{\epsilon}$  and  $\gamma_{\epsilon}$ ) because jump time increments  $\delta$  typically take too large values and to control the error at every step we should truncate those times at a sufficiently small  $h > 0$  for a satisfactory accuracy.

# Conclusions

- Using probabilistic representations, we can approximate various problems for parabolic and elliptic 2nd order PDEs and PIDEs.
- We considered simplest (and hence easy to implement) algorithms for:
  - Dirichlet problems for linear parabolic and elliptic PDEs
  - Robin problems for linear parabolic and elliptic PDEs
  - Dirichlet problem for linear parabolic PIDE